Claims

- 1. Method for kick-down switching speed optimization in a motor vehicle with an automatic transmission, characterized in that the kick-down upswitch point is determined as a function of the load conditions and road inclination in each case.
- 2. Method according to Claim 1, characterized in that when a kick-down condition is recognized by the transmission control system, a speed offset of appropriate sign (nd_abkd) is added to the current upshift point as a function of the output speed gradient (ng_ab).
- 3. Method according to Claim 2, characterized in that the variation of the speed offset of appropriate sign (nd_abkd) is stored in the transmission control system in the form of a characteristic line a separate characteristic line being stored for each upshift.
- 4. Method according to Claim 1, characterized in that an absolute kick-down switching characteristic line is used for the determination of the kick-down upshift point.
- 5. Method according to Claim 1, characterized in that when a kick-down condition is recognized, the target gear for the next upswitch and the transmission output speed gradient (ng_ab) are determined and the speed offset (nd_abkd) is then calculated, the delay times for individual gear changes being stored for application and temperature-dependent delay times being taken into account.
- 6. Method according to any of Claims 2 to 6, characterized in that the value of the speed offset (nd_abkd) is calculated, and is then recalculated as a function of the existing driver behavior, in such manner that the upshift speed (n_abkd) is adapted to the driver's way of driving.
- 7. Method according to Claim 6, characterized in that the value of the speed offset (nd_abkd) is re-calculated as a function of driver activity by multiplying the characteristic line (nd_abkd) by a factor that depends on driver behavior.

8. Method according to Claim 6, characterized in that the value of the speed offset (nd_abkd) is re-calculated as a function of driver activity by establishing characteristic lines for each characteristic type of driver, intermediate values being determined by averaging between the driver types.